

APPLICATION  
FOR  
UNITED STATES LETTERS PATENT  
ENTITLED

DYNAMIC PERFORMANCE MEASURES

TO WHOM IT MAY CONCERN:

BE IT KNOWN THAT (1) MELANIE RUSSELL and (2) FAYYAZ HUSSEIN,  
of (1) ADDRESS and (2) ADDRESS, invented certain new and useful  
improvements entitled as set forth above of which the following  
is a specification:

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3 DYNAMIC PERFORMANCE MEASURES  
4

5 BACKGROUND OF THE INVENTION  
6

(1) Field of the Invention

The present invention relates generally to process control indicators and more particularly to real-time indicators for improved performance process control.

(2) Description of the Prior Art

In a process plant, various processes are employed to produce amounts of a desired product. Traditional methods to measure general performance of manufacturing operations of a certain product include counting the amount of product produced over a certain period of time, and from that amount, calculating a cost per unit product. The cost per unit product is typically based on a standard cost function that is associated with the operation, often developed at the beginning of a fiscal time period, and utilized throughout that period. The cost per unit product is also often reported to manufacturing management to evaluate manufacturing performance, and often serves as a primary measure of manufacturing performance.

One disadvantage of measuring manufacturing performance by cost per unit product is the equal distribution and allocation of

1 plant costs to each product or product line in the determination  
2 of cost per unit product. Most costs in a manufacturing plant  
3 are not directly assignable to a product or product line, and  
4 therefore costs must be allocated as a function of other factors  
5 that usually have more to do with the perceived performance of  
6 the manufacturing operation than the actually occurring  
7 manufacturing practices.

8 A second disadvantage of measuring manufacturing performance  
9 by cost per unit product is that a considerable percentage of the  
10 costs in a manufacturing plant for calculating the cost per unit  
11 product, are not within the scope of manufacturing's authority;  
12 therefore, the performance measurement of cost per unit product  
13 leads to a "volume base" manufacturing approach that may not  
14 properly satisfy market and corporate requirements.

15 Another disadvantage is that the calculation to determine  
16 cost per unit product is a function of the amount of each product  
17 or product line produced, and this calculation is not sensitive  
18 to problems incurred in the producing a specific product. For  
19 example, if a bad batch of a given product is produced and  
20 discarded, a standard allocation algorithm cannot assign the  
21 costs associated with that batch to the specific product, and the  
22 costs are allocated to all products.

23 Other approaches to measuring manufacturing performance  
24 involve non-cost/non-financial measurements and include

1 measurements of quality, delivery integrity and customer  
2 satisfaction. These approaches are generally directed to the  
3 discrete manufacturing industry and involve collecting  
4 information and displaying results in a traditional daily,  
5 weekly, or monthly report format. Such approaches do not provide  
6 timely measurements to allow operations personnel to improve the  
7 process on which the measurements were made.

8 There is currently not any sufficient systems or methods for  
9 generating timely measurements of manufacturing systems  
10 operations in the cement industry.

11 What is needed are methods and systems that allow cement  
12 industry manufacturing systems personnel to measure manufacturing  
13 processes to improve plant operations performance.

14

15 SUMMARY OF THE INVENTION

16 The systems and methods disclosed herein provide a real-time  
17 (dynamic), sensor-based performance control apparatus that can be  
18 utilized in a cement production process. The control apparatus  
19 can employ a multiplicity of sensors and a computer processor for  
20 providing a real-time indication of operating performance from  
21 sensor signals. Performance can be indicated in terms of quality  
22 of generated products, cost of production, down-time, yield,  
23 and/or production.

1            Sensors can provide signals indicative of current state of a  
2        respective process. A digital processor assembly can be coupled  
3        to the sensors to receive the sensor signals. A computer can  
4        support the digital processor to determine, from the sensor  
5        signals, a quantitative measurement of current performance of the  
6        manufacturing operations based on current operation of at least  
7        one process. For example, the computer can calculate production  
8        cost as a function of sensed current amounts of resources used,  
9        and calculate quantity of production as a function of sensed rate  
10      of operation of certain processes.

11           The computer can further provide screen views displayed on a  
12        video display coupled to the digital processor assembly. The  
13        screen views can display indications of the determined  
14        measurement of current performance of manufacturing operations  
15        with respect to a predetermined target performance measurement.  
16        Subsequent operator adjustment through the control apparatus that  
17        is coupled to the process, in accordance with the indications in  
18        the screen views, can cause states of the process to approach  
19        operation that provides a predetermined target performance of the  
20        manufacturing operations.

21           Along with screen view displays, the computer can provide  
22        audible and/or visible alarms in accordance with determined  
23        performance measurements. The alarms can be coupled to the  
24        digital processor assembly. For example, the computer can

1 provide an alarm when certain criteria are satisfied by a process  
2 and/or by determined performance. For example, the computer can  
3 enable an alarm when a determined performance measurement based  
4 on current cost of production exceeds a predefined threshold,  
5 and/or when determined performance measurement based on quality  
6 is outside a predefined range.

7 In accordance with the methods and systems herein related to  
8 a cement processing operation, sensors can include temperature  
9 sensors, weight sensors, pressure sensors, etc.

10 In one embodiment, the digital processor assembly can  
11 include processor modules. Different sensors can be coupled to  
12 the different processor modules. Processor modules can have an  
13 object manager to transmit respective sensor signals to a  
14 computer upon request by the computer. Sensor signals can be  
15 formed of a named series of data points stored in a memory area,  
16 and object managers can enable access of data points by name  
17 instead of memory location.

18 The computer can be coupled to an external system for  
19 receiving pertinent predefined measurements of target  
20 performance. A control apparatus can be coupled to the digital  
21 processor assembly. Additionally, a processor member supported  
22 by the digital processor assembly can receive working data from  
23 the computer and store the working data on a common time-line in  
24 a global database for general access. The working data can

1 include determined performance measurements, predetermined target  
2 measurements, indications of sensed states of process means,  
3 operator adjustments, and predefined thresholds for alarms. In  
4 one embodiment, the database can be a relational database  
5 accessible globally at subsequent times as desired for different  
6 applications.

7 In an embodiment wherein the methods and system disclosed  
8 herein can be applied to generate an advanced control solution  
9 for a cement production system, the systems and methods can be  
10 applied to a wet cement manufacturing process. In another  
11 embodiment, the systems and methods can be applied to a dry  
12 cement manufacturing process. In a cement production system,  
13 sensors can provide measurements that can be related to the  
14 efficiency of a kiln and a finishing mill that can be integral to  
15 cement production quantity, quality, and cost. The sensor  
16 measurements can be related to kiln and finishing mill cost and  
17 production to allow manufacturing, engineering, operations, or  
18 other personnel to alter processes and adjust the kiln and  
19 finishing mill cost and production measures accordingly.

20 In an embodiment, kiln production can be measured and  
21 monitored as a function of feed to the kiln less dust loss. Kiln  
22 cost can thereafter be computed as a function of kiln production.

23 Alternately, finish mill can measure throughput as a function of  
24 the fresh feed produced in tons per hour. Finish mill production

1 costs can be computed as a function of the finish mill throughput  
2 and energy costs.

3 Other objects and advantages of the invention will become  
4 obvious hereinafter in the specification and drawings.  
5

6 BRIEF DESCRIPTION OF THE DRAWINGS

7 A more complete understanding of the invention and many of  
8 the attendant advantages thereto will be readily appreciated as  
9 the same becomes better understood by reference to the following  
10 detailed description when considered in conjunction with the  
11 accompanying drawings, wherein like reference numerals refer to  
12 like parts and wherein:

13 FIG. 1 is a description of a cement production process as is  
14 commonly known in the art;

15 FIG. 2 is an illustration of Dynamic Performance Measures  
16 (DPMs) for the cement production process of FIG. 1;

17 FIG. 3A, 3B, 3C, and 3D present other displays that can be  
18 generated from the DPM data of FIG. 2; and,

19 FIG. 4 provides an illustrative system for one embodiment of  
20 the invention that utilizes the I/A Series system.  
21

22 DESCRIPTION OF ILLUSTRATED EMBODIMENTS

23 To provide an overall understanding of the invention,  
24 certain illustrative embodiments will now be described; however,

1 it will be understood by one of ordinary skill in the art that  
2 the methods and systems described herein can be adapted and  
3 modified to provide methods and systems for other suitable  
4 applications and that other additions and modifications can be  
5 made to the invention without departing from the scope hereof.

6 FIG. 1 shows an illustrative block diagram of a cement  
7 product process 10 for a dry production process. As FIG. 1  
8 indicates, limestone from a quarry 12 can be presented to a  
9 crushing area 14 where it can be reduced to gravel size pieces  
10 for presentation to a grinding area 16. The grinding area 16  
11 blends raw materials in the proper proportions and grinds them  
12 into a powder than can otherwise be known as Raw Meal. In an  
13 alternate embodiment not shown in FIG. 1 and known as a wet  
14 production process, water can be added to the raw feed during the  
15 grinding process 16 to create a mixture called slurry. For the  
16 purposes of the discussion herein, the FIG. 1 system shall be  
17 understood to represent the well-known wet and dry processes, and  
18 in accordance therewith, Raw Meal shall be understood to include  
19 slurry. Returning to process referenced by FIG. 1, the Raw Meal  
20 is presented to the Clinker Production area 17 that can include a  
21 four stage Preheater 18, a Precalciner 20, a Kiln 22, and a  
22 Cooling Area 24, although those with ordinary skill in the art  
23 will recognize that the illustrated Clinker Production area 17 is  
24 provided for illustration and not limitation, and fewer, more,

1 and/or substitute components of a Clinker Production area 17 can  
2 be provided without departing from the scope of the invention.  
3 The illustrated Preheaters 18 are vertical cyclone chambers  
4 through which the Raw Meal passes. The Precalciner 20 accepts  
5 the Raw Meal from the last stage of the Preheaters 18, and  
6 performs a partial calcination process by introducing fuel,  
7 thereby removing carbon dioxide. In the illustrated system, the  
8 fuel is coal, although those with ordinary skill in the art will  
9 recognize that other fuels can be used for the calcination  
10 process, and other systems may use Pre-heaters with other numbers  
11 of stages. After the passing through the Precalciner 20, the  
12 material previously known as Raw Meal and heretofore referred to  
13 as "the material" moves into the kiln 22, wherein remaining  
14 carbon dioxide is removed and the intense heat begins to trigger  
15 chemical reactions that turn the material, now precalcined, into  
16 clinker. In the illustrated kiln 22, the material temperature  
17 can reach twenty-seven hundred degrees towards the discharge end  
18 of the kiln 22, wherein the material begins to form nodules that  
19 can otherwise be termed clinker. In the FIG. 1 system 10, the  
20 clinker retreats to the cooling area 24 where fans force cool air  
21 over the clinker. In the illustrated system, the heat recovered  
22 from the cooled clinker can be partially returned to the kiln 22  
23 as secondary air to assist the primary combustion.

1           In a finish mill 26, clinker from the cooling area 24, known  
2       otherwise as fresh feed, can be mixed with gypsum, slag, rich  
3       limestone, etc., before being fed into a grinding mill that  
4       grinds the treated clinker into a very fine powder. A separator  
5       28 can accept the fine powder from the finish mill 26 and  
6       distinguish between material that does and does not meet fineness  
7       requirements. Material meeting the fineness requirement can be  
8       stored in cement storage silos 30 for shipping at a later time,  
9       while material not satisfying the fineness requirement can be  
10      returned to the finish mill 26 as "reject" and combined with  
11      fresh feed from the cooling area.

12           From the process of FIG. 1, it can be shown that a critical  
13      part of the cement production process includes the making of  
14      clinker. For systems according to FIG. 1, a clinker factor can  
15      be computed and verified to satisfy a clinker production  
16      efficiency. For example, a clinker factor of fifty-six one-  
17      hundredths can indicate that for every ton of material that  
18      enters the kiln 22, fifty-six one-hundredths of a ton of clinker  
19      is produced. Fuel rate and feed rate to the kiln can therefore  
20      be determined to be important factors to clinker production.

21           For the system of FIG. 1 wherein maximization of clinker  
22      production for minimal cost is desired, a dynamic performance  
23      measure (DPM) can be defined to maximize throughput of the  
24      clinker production area 17, increase clinker quality, measure

1       burning efficiency, and optimize refractory life. DPMs are  
2       metrics that model performance measures in process manufacturing  
3       operations, wherein the metrics are derived from process  
4       instrumentation. DPMs can thus be calculated from a production  
5       process using real-time, preferably object-based process data to  
6       display results in real-time to operations, engineering,  
7       maintenance, and/or appropriate manufacturing or other personnel,  
8       as decision support tools for real-time plant operations. In an  
9       embodiment, the DPMs can be presented graphically, and the DPM  
10      results can be historized into a real-time database management  
11      system for later use, aggrandizement, and integration with other  
12      computer information systems of the manufacturing plant.

13      DPMs for a particular plant operation can be a function of  
14      the manufacturing strategy for that operation. The DPMs for one  
15      process or group thereof in one plant may not be appropriate for  
16      the same process of a similar but different plant. For example,  
17      if a manufacturing or process plant is production limited,  
18      primary measures can include yield or some other production-based  
19      statistic; but, if a manufacturing or process plant is not  
20      production limited, primary measures can be more resource-based.  
21      Developing DPMs therefore includes determining a manufacturing  
22      strategy, and translating that strategy to specific measurements  
23      that can assist in determining whether the strategy is

1           successful, and this success can be measured on a process-by-  
2           process basis.

3           Once specific measures are determined, sensor information to  
4           make the measures can be determined. In many manufacturing and  
5           process plants, the sensors to make the measures are already  
6           installed in the manufacturing or control process. In some  
7           cases, new sensors can be installed to complete the collection of  
8           sensor-based information to measure the manufacturing or process  
9           operations.

10          The sensor measurements can be input to a computer or other  
11         processing module. In an embodiment, the sensors can transmit a  
12         digital or analog signal to the computer that is equipped with  
13         appropriate input/output capability to receive the sensor-based  
14         information. The computer can convert, as necessary, the  
15         incoming sensor signals into digital values that can be formed  
16         into an input block that includes a collection of records or  
17         fields for sensor data. In an embodiment, a particular input  
18         block corresponds to a particular sensor. An input block can  
19         also provide general system access to the sensor data by name,  
20         where the global name is based on the name assigned to the input  
21         block. This data point or "object" value can be available to any  
22         application on the computer, or to other computers in a network  
23         to which the computer is connected, by specifying the name of any

1       input block or the name of the field or record of interest in the  
2       input block.

3           Calculation algorithms can also be formulated as part of the  
4       DPM construction. The calculation algorithms can mathematically  
5       relate the sensor measurements to a measure of the manufacturing  
6       strategy. The calculation algorithms can also include targeted  
7       values, predetermined values, and comparisons between currently  
8       calculated values and the target values.

9           In an embodiment, an object oriented programming based block  
10      structure can be established for a computation algorithm. These  
11      algorithm blocks can be preprogrammed for DPMs that are  
12      frequently encountered, or they can be programmed for different  
13      applications. The sensor-based data provides the input to the  
14      algorithm blocks, and this can be accomplished by identifying in  
15      the algorithm block, an input block name and an input block  
16      parameter (field or record) of interest. The sensor data can  
17      therefore be input to the algorithm block and manipulated  
18      according to the mathematical relationships in the algorithm  
19      block.

20           The algorithm block output can be a global object that can  
21      be accessed by the computer or another computer in a network, for  
22      example, by specifying the name of the producing algorithm block.

23           The output object values can be a basis for the DPMs of  
24      interest.

1           In an embodiment, in an algorithm block, the current overall  
2 performance of a manufacturing or plant operation can be computed  
3 as a function of the sensor measurements. The calculated  
4 performance can be compared to a targeted performance measure as  
5 stored in, for example, an algorithm block or in a historian  
6 database. The comparison results can be presented to a display  
7 object and/or a historical database.

8           Display objects and display templates can be constructed for  
9 standard presentations of the DPMs, and can include line graphs  
10 that depict the DPM value over a period of time (historized), an  
11 indication of the DPM target value, an indication of any  
12 pertinent alarm limits. In an embodiment, the x and y axes can  
13 be labeled for the application and include a directional  
14 indicator showing the direction of increasing performance.  
15 Display objects can be combined with other graphics to build an  
16 entire display template.

17           Subsequent to the building and displaying of the comparison  
18 results in various display objects, an operator/user can adjust  
19 controls and hence processes accordingly. The real-time display  
20 of the compared calculated performance and target performance in  
21 terms of production/resource factors of administration, enables  
22 operator adjustment of processes, and hence resource/production  
23 factors, immediately during subject manufacturing toward target  
24 performance, i.e., toward desired values of resource/production

1 factors. These adjustments can be recorded in a historian  
2 database. A historian database can therefore include sensed  
3 states of processes, operator adjustments, calculated performance  
4 measurements, and predefined target measures.

5 Returning now to the generalized cement processing system  
6 shown in FIG. 1, wherein manufacturing strategies include the  
7 maximization of clinker production while minimizing cost, DPM  
8 calculation algorithms can be defined as follows:

9

$$10 \quad \text{Clinker Production} = (\text{feed to kiln} - \text{dust loss}) * .56 \\ 11 \quad \text{tons/hour} \quad (1)$$

12

13 The "feed to kiln" can be either slurry or raw meal, depending  
14 upon the wet or dry process, respectively. The computation for  
15 clinker production of Equation (1) can also be interpreted and  
16 expressed as a computation for kiln production. Alternately,  
17 Clinker cost can be expressed as:

18

$$19 \quad \text{Cost per ton of Clinker} = (\text{Fixed Cost} + \text{Energy Cost} + \text{Fuel} \\ 20 \quad \text{Cost} + \text{Raw Material Cost} + \text{Losses}) / (\text{Clinker Production}) \quad (2)$$

21

22 If it is assumed that Fixed Cost and Raw Material Cost are  
23 not variable and not subject to control by the operations or  
24 other management personnel, etc., Equation (2) can be reduced and

1 expressed as a function of Equation (1) to represent the kiln  
2 cost per ton of clinker, or more simply, cost per ton of clinker:  
3

4 Cost per ton of Clinker = (KWH\*Cost of KWH) + (Coal feed  
5 rate\*Cost of coal) + (Other fuel feed rate\*Cost of other  
6 fuel))/((feed to kiln - dust loss)\*.56 tons/hour) (3)

7  
8 Those with ordinary skill in the art will recognize that  
9 Equation (3) is computed with respect to tons, and therefore  
10 items such as "coal feed rate" and "other fuel feed rate" should  
11 be expressed in tons/hour. In Equation (3), other fuel feed rate  
12 are variable and controllable, while the costs of the respective  
13 quantities or measures (e.g., costs of KWH, coal, other fuel(s))  
14 are not controllable and can be fixed or dictated by an outside  
15 source or vendor.

16 In an embodiment, waste fuels can supplement coal feed,  
17 wherein the cement manufacturer, etc., is paid to accept and  
18 include the waste fuels with the coal feed at the input to the  
19 kiln and/or precalciner. In an embodiment wherein waste fuels  
20 are utilized, the cost of per ton of clinker as provided in  
21 Equations (2) and (3) herein, can be modified by subtracting an  
22 amount equal to the waste fuel credit in tons per hour.

23 For the illustrative system of FIG. 1, the kiln sensors can  
24 provide measurements including kiln feed, temperature

measurements at the input and output of the preheater stages, water content at the preheater stages, oxygen and carbon-monoxide, cooling fan rotation and power (current, voltage, etc.), coal feed and BTUs, secondary air temperature, cooler vent temperature, clinker temperature in the cooling area, oil flow, fan speed, damper, etc., and such measurements are provided for illustration and not limitation. Those with ordinary skill in the art will recognize that the invention herein is not limited to the sensors, the sensor arrangement, or the format of the sensor input or output. Any sensor or sensor measurement that can be incorporated into a clinker production factor or a cost per ton of clinker according to Equations (1) and (3) herein is within the scope of the invention. Additionally, system variables, including for example, stack particulates and residual carbonate, although not measured directly, can be inferred using a non-linear modeling technique based on neural networks.

Multivariable control can be implemented to control the process (e.g., kiln) by comparing measured temperatures to theoretical or ideal temperatures and automatically making the necessary adjustments. For example, a multivariable control system such as the Connisseur System by Invensys Systems, Inc., can utilize neural networks and/or fuzzy logic, although the invention herein is not limited to such embodiments.

A second DPM can be provided for the Finish Mill 26 to maximize throughput, minimize energy consumption, and minimize recirculating load. For the Finish Mill 26, the following computational algorithms can be developed:

Finish Mill Throughput = fresh feed to finish mill  
(tons/hour) (4)

Referring to FIG. 1 with reference to Equation (4), the fresh feed to the Finish Mill 26 is the amount of clinker input to the finish mill. This fresh feed measurement does not include reject as shown in FIG. 1, and although the FIG. 1 system indicates that clinker from the kiln is input to the Finish Mill 26, it is not unusual for the fresh feed measurement to include clinker from sources other than the kiln (i.e., cement processors can purchase clinker from alternate sources).

Another algorithm relating to the Finish Mill 26 includes the cost of cement:

$$\text{Cost per ton of cement} = (\text{Fixed Cost} + \text{Energy Cost} + \text{Raw Material Cost} + \text{Losses}) / (\text{Fresh Feed}) \quad (5)$$

Once again, by eliminating the non-variable Fixed Cost and Raw Material Cost from Equation (5), and incorporating Equation

(4) into Equation (5), the Cost per ton of cement ("Finish Mill Cost") can also be expressed as:

Cost per ton of cement = ((KWH\*Cost of KWH) + (Clinker Feed Rate\*Cost of Clinker) + (Gypsum Feed Rate\*Cost of Gypsum) + (Grinding Aide Feed Rate\*Cost of Grinding Aide)/((Fresh Feed) - Reject)). (6)

Once again, in equations (5) and (6), quantities are understood to be expressed in consistent units of tons/hour. Fixed Cost and Raw Material Cost are not subject to control, while Energy Cost (i.e., Clinker feed rate) and Losses (i.e., Grinding Aide feed rate) are variable and controllable by an operator, management personnel, etc. Similarly, the Gypsum feed rate is variable and controllable. Once again, costs of respective elements (e.g., costs of KWH, Gypsum, Grinding Aide) can be fixed by an outside source or vendor. The Cost of Clinker can be determined from Equation (3), and can be variable depending upon factors discussed previously in relation to Equation (3). The Clinker Feed Rate as indicated by Equation (6) represents the feed rate of Clinker to the Finish Mill **26** for the representative system of FIG. 1.

For example, in the illustrated finish mill, measurements can include feed at the input, reject at the input, energy, water

1 content, power, temperature, etc. Those with ordinary skill in  
2 the art will recognize that the invention is not limited to these  
3 parameters or the sensors for measuring the same, and the  
4 invention includes any and all sensors and measurements that can  
5 contribute to the determination of the factors of equations (4)  
6 and (6) for the computation of the finish mill throughput and the  
7 cost per ton of cement. Once again, depending upon the  
8 computations of Equations (4) and (6), multivariable control can  
9 be employed to perform automatic adjustment of sensors,  
10 processes, etc., using mechanisms that can include neural  
11 networks, fuzzy logic, etc.

12 In an embodiment, Operator displays for the two DPMs can be  
13 provided on a single display, and can include metrics for clinker  
14 (i.e., kiln) production, clinker (i.e., kiln) cost, finish mill  
15 production, and finish mill cost. In another embodiment,  
16 multiple displays can be used. As FIG. 2 indicates, the four  
17 metrics can be provided as a function of time to an operator or  
18 other user. An operator or other user viewing the DPMs can  
19 determine instantaneously whether the production and/or cost  
20 goals are being satisfied. As indicated earlier, alarms can be  
21 used to alert the user to such conditions. Upon determining that  
22 the production and/or cost goals are not being satisfied, the  
23 user can determine whether one or more of the system variables  
24 requires modification or adjustment. As also indicated earlier,

1       adjustments can be provided automatically using a multivariable  
2       controller that can implement fuzzy logic, neural networks, or  
3       other well-known techniques for classifying system conditions  
4       and/or automating a controlled response.

5       In an embodiment, existing or new sensors measuring the KWH  
6       of the kiln, the coal feed rate, fuel rate, feed, dust loss, and  
7       the KWH of the finish mill, the clinker feed rate, gypsum feed  
8       rate, grinding aide feed rate, fresh feed, and rejects, can  
9       provide data that can be formed into input blocks, submitted  
10      respectively to the computational algorithms as presented by  
11      equations (3) and (6) to develop one or more display objects as  
12      indicated in FIG. 2, for example. The presentation of such  
13      information in real-time can allow an operator, user, etc., to  
14      correlate a change in production or cost performance relative to  
15      one of the parameters. An operator, engineer, etc., can view the  
16      dashboard displays and make adjustments to the various parameters  
17      to determine how the Clinker Production and Finish Mill  
18      Production are affected as a function of cost. Those with  
19      ordinary skill in the art will recognize that the sensor  
20      measurements can be filtered and otherwise processed to eliminate  
21      noise or other undesired signals or signal components.  
22      Additionally, the processed or unprocessed sensor signals can be  
23      provided as input to a neural network or fuzzy logic to detect,  
24      for example, sensor failures and other conditions that can

1 warrant intervention of engineering or operations personnel.

2 Sensor failure conditions can also cause an alarm in an  
3 embodiment.

4 FIG. 3A shows an alternate method for displaying the  
5 information from the input blocks formed by the DPM process  
6 described herein based on the FIG. 1 system. FIG. 3A presents a  
7 daily display of Cement costs versus Clinker costs. FIG. 3B  
8 provides an analysis of KWH for the Grinding Area, Raw Mill, and  
9 Finish Mills. FIG. 3C illustrates Clinker Area Production versus  
10 Cost for real-time and Year-to-date, while FIG. 3D presents the  
11 difference, per day, in cost between a target cost and actual  
12 costs. Those with ordinary skill in the art will recognize that  
13 although the charts and figures of FIGS. 3A-3D were presented in  
14 particular display formats, the invention herein is neither  
15 limited to the information displayed, nor the format of the  
16 displayed information.

17 Referring now to FIG. 4, there is shown an illustrative  
18 system 40 that can be implemented in a cement production  
19 manufacturing process such as the system of FIG. 1, can further  
20 provide for implementation of DPMs as provided herein, and is  
21 known as the I/A Series ® system from Invensys Systems, Inc. As  
22 is well-known, the I/A Series ® system includes I/O Modules 42  
23 such as the FBM44 modules, wherein the I/O Modules 42 can  
24 interface to a Fieldbus 43 and hence to a Control Processor 44

such as the I/A Series ® CP40B. Data from sensors 46 can be transferred to the I/O modules 42 using a transmitter, wherein the I/O Modules 42 can convert the sensor data to a format compatible with the Control Processor 44. In one embodiment of the system, the Control Processor 44 can include at least one processor that includes instructions for causing the processor to implement control algorithms. The Control Processor 44 can further include instructions for implementing DPMs such as those provided herein by Equations (1) through (6). As shown for the FIG. 4 system, the Control Processor 44 can interface to Workstations 48 through an I/A Series Nodebus 50 that can be compatible with Ethernet. The Workstations can be, for example, the I/A Series system AW51E that or any other system that provides the functionality described herein. The Workstations 48 can allow for the display of data such as that according to FIGs. 3A-3D herein to allow a processor engineer, manufacturing personnel, etc., to monitor and/or affect the controlled systems.

The illustrated Workstations 48 can further interface to another Ethernet 52 that provides an interface to, for example, a corporate network that can be equipped with other Workstations 54, Personal Computers (PCs), etc., that can also have instructions for causing the display of DPM and/or other information to management or other entities. Historic

1 information can also be provided to such systems 54 for local  
2 retrieval and analysis.

3 Returning to the Control Processor 44 of FIG. 4, depending  
4 upon the control algorithms, DPM computations, and any  
5 integration therein, the Control Processor 44 can be equipped to  
6 transfer control data to, for example, the valves or sensors 46  
7 via the I/O Modules 42 to achieve specified control objectives.  
8 In one embodiment, the control objectives can be pre-programmed  
9 using a multivariable control system such as the Foxboro  
10 Connisseur system, however in other embodiments, manufacturing or  
11 other process system adjustments can be made manually or through  
12 the I/A Series Workstations 48.

13 One of several advantages of the present invention over the  
14 prior art is that dynamic performance measures are generated to  
15 relate sensor measurements in a cement processing system to  
16 identifiable management goals of balancing cement production and  
17 efficiency against production costs.

18 What has thus been described are methods and systems for  
19 creating dynamic performance measures (DPMs) for a cement  
20 production system. In an embodiment, clinker production and  
21 finish mill production can be optimized by aggregating sensor  
22 measurements from clinker production and finish mill production  
23 processes, and determining measures in the form of DPMs related  
24 to the productivity and cost of the clinker production and finish

1 mill production. The DPMs can be provided to a display that can  
2 be viewed by manufacturing or other personnel. Control decisions  
3 can be made to change the clinker production and/or finish mill  
4 production processes while the results of such changes can be  
5 reflected in real-time on the DPM displays.

6 Although the present invention has been described relative  
7 to a specific embodiment thereof, it is not so limited.  
8 Obviously many modifications and variations of the present  
9 invention may become apparent in light of the above teachings.  
10 For example, any sensors providing the necessary sensor  
11 measurements can be used to construct the desired DPMs, and the  
12 invention can utilize any sensors that provide measurements  
13 according to equations (1), (3), (4), and (6). The block diagram  
14 of the cement production process is merely illustrative and not  
15 intended for limitation, and alternate cement production elements  
16 can be included or otherwise eliminated without departing from  
17 the scope of the invention. Although the equations were  
18 presented for units of tons or tons/hour, other units of  
19 measurement and/or time can be utilized to modify the equations  
20 accordingly.

21 Many additional changes in the details, materials, steps and  
22 arrangement of parts, herein described and illustrated to explain  
23 the nature of the invention, may be made by those skilled in the  
24 art within the principle and scope of the invention.

1 Accordingly, it will be understood that the invention is not to  
2 be limited to the embodiments disclosed herein, may be practiced  
3 otherwise than specifically described, and is to be understood  
4 from the following claims, that are to be interpreted as broadly  
5 as allowed under the law.

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